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 $0.25e^{-2t} + 0.25 +$   
 $0.5t - e^{-1}t^2 + 2e^{-1}t^3 - 2$   
 $[r,p,k] = \text{residue}([4,3],[$   
 $1,6,34,0])$  The result  
is  $r = [-0.0441 -$   
 $0.3735i, -0.0441 +$



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$0.3735i, 0.0882]$ ,  $p =$   
 $[-3.0000 + 5.0000i,$   
 $-3.0000 - 5.0000i, 0]$ ,  
and  $k = [ ]$ . The

solution is  $x(t) =$

$(0.0441 ?$

$0.3735j)e^{(3+5j)t} +$

$(0.0441 +$

$0.3735j)e^{(3-5j)t} +$

$0.0882$  The solution is

$x(t) = 2e^{-3t} (0.0441$

$\cos 5t + 0.3735 \sin 5t)$

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The characteristic equation derived earlier becomes  $s^2 + 3s + 1 = 0$ . The roots are  $s = -2.618$  and  $s = -0.382$ .

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The dominant time constant is  $1/3.82=0.262$ , and thus we would expect the steady-state response to be reached in about  $4(0.262)=1.04$  s. The scope plot confirms this. 16.

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asked in the 3rd edition of System Dynamics: Consider the two-mass model shown in Figure P11.50. Use the following numerical values:  $m_1 = m_2 = 1$ ,  $k_1 = 1$ ,  $k_2 = 4$ , and  $c_2 = 8$ . a. Use MATLAB to obtain the root locus plot in terms of the parameter  $c_1$ . b.

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1) You can substitute the form (5) into the differential equation and use the initial conditions to obtain equations for the  $C_i$  coefficients. 2) You can



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use (1) and (2) to create a partial fraction expansion of (4) in terms of the complex factors. 3) You can perform an expansion in terms of the six roots, of the form  $A_1$ .

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