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The Book of R is a comprehensive, beginner-friendly guide to R, the world's most popular programming language for statistical analysis. Even if you have no programming experience and little more than a grounding in the basics of mathematics, you'll find everything you need to begin using R effectively for statistical analysis. You'll start with the basics, like how to handle data and write simple programs, before moving on to more advanced topics, like producing statistical summaries of your data and performing statistical tests and modeling. You'll even learn how to create impressive data visualizations with R's basic graphics tools and contributed packages, like ggplot2 and ggvis, as well as interactive 3D visualizations using the rgl package. Dozens of hands-on exercises (with downloadable solutions) take you from theory to practice, as you learn: –The fundamentals of programming in R, including how to write data frames, create functions, and use variables, statements, and loops –Statistical concepts like exploratory data analysis, probabilities, hypothesis tests, and regression modeling, and how to execute them in R –How to access R's thousands of functions, libraries, and data sets –How to draw valid and useful conclusions from your data –How to create publication-quality graphics of your results Combining detailed explanations with real-world examples and exercises, this book will provide you with a solid understanding of both statistics and the depth of R's functionality. Make The Book of R your doorway into the growing world of data analysis.

Design, build and simulate complex robots using Robot Operating System and master its out-of-the-box functionalities About This Book Develop complex robotic applications using ROS for interfacing robot manipulators and mobile robots with the help of high end robotic sensors Gain insights into autonomous navigation in mobile robot and motion planning in robot manipulators

Discover the best practices and troubleshooting solutions everyone needs when working on ROS Who This Book Is For If you are a robotics enthusiast or researcher who wants to learn more about building robot applications using ROS, this book is for you. In order to learn from this book, you should have a basic knowledge of ROS, GNU/Linux, and C++ programming concepts. The book will also be good for programmers who want to explore the advanced features of ROS. What You Will Learn Create a robot model of a Seven-DOF robotic arm and a differential wheeled mobile robot Work with motion planning of a Seven-DOF arm using MoveIt! Implement autonomous navigation in differential drive robots using SLAM and AMCL packages in ROS Dig deep into the ROS Pluginlib, ROS nodelets, and Gazebo plugins Interface I/O boards such as Arduino, Robot sensors, and High end actuators with ROS Simulation and motion planning of ABB and Universal arm using ROS Industrial Explore the ROS framework using its latest version In Detail The area of robotics is gaining huge momentum among corporate people, researchers, hobbyists, and students. The major challenge in robotics is its controlling software. The Robot Operating System (ROS) is a modular software platform to develop generic robotic applications. This book discusses the advanced concepts in robotics and how to program using ROS. It starts with deep overview of the ROS framework, which will give you a clear idea of how ROS really works. During the course of the book, you will learn how to build models of complex robots, and simulate and interface the robot using the ROS MoveIt motion planning library and ROS navigation stacks. After discussing robot manipulation and navigation in robots, you will get to grips with the interfacing I/O boards, sensors, and actuators of ROS. One of the essential ingredients of robots are vision sensors, and an entire chapter is dedicated to the vision sensor, its interfacing in ROS, and its programming. You will discuss the hardware interfacing and simulation of complex robot to ROS and ROS Industrial (Package used for interfacing industrial robots). Finally, you will get to know the best practices to follow when programming using ROS. Style and approach This is a simplified guide to help you learn and master advanced topics in ROS using hands-on examples.

This book will show you how to use your Arduino to control a variety of different robots, while providing step-by-step instructions on the entire robot building process. You'll learn Arduino basics as well as the characteristics of different types of motors used in robotics. You also discover controller methods and failsafe methods, and learn how to apply them to your project. The book starts with basic robots and moves into more complex projects, including a GPS-enabled robot, a robotic lawn mower, a fighting bot, and even a DIY Segway-clone. Introduction to the Arduino and other components needed for robotics Learn how to build motor controllers Build bots from simple line-following and bump-sensor bots to more complex robots that can mow your lawn, do battle, or even take you for a ride Please note: the print version of this title is black & white; the eBook is full color.

The increase in demand for electricity and the growing energy density in metropolitan cities have made it necessary to extend the existing high voltage network right up to the consumer. Stepping down the voltage from transmission to the distribution level at the substations located near the actual consumers not only yields economic advantages, but also ensures reliable power supply. Such substations are required to meet a number of severe requirements, including small installation size, effective protection against atmospheric pollution and moisture, noiseless operation, nonexplosive and flame resistant, reduced maintenance, minimal radio interference while providing excellent electric characteristics. Conventional substations using atmospheric air as the main dielectric cannot satisfy these requirements, but totally enclosed substations using sulphur hexafluoride (SF6) gas insulation that are also known as Gas Insulated Substations (GIS). GIS is now in widespread use in the electrical power industry, especially in metropolitan areas. This book will serve as a valuable reference for the novice as well as the expert who needs a wider and detailed scope of coverage within the area of GIS. Gas Insulated Substations provides a comprehensive coverage of a wide range of topics which include: " Introduction to GIS & Properties of SF6 " Layout, Design, Construction, Testing & Maintenance of GIS " Special Problems and Diagnostic Techniques " VFTO Phenomena and its Effects in GIS " Service Experience " Standards Specifications " Future Trends " Extensive References Gas Insulated Substations (GIS) is the first single source for authoritative information on the state of the art in GIS.

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